

Orthogonal Matrices & Symmetric Matrices

Hung-yi Lee

Outline

Orthogonal Matrices

- Reference: Chapter 7.5

Symmetric Matrices

- Reference: Chapter 7.6

Norm-preserving

- A linear operator is norm-preserving if

$$\|T(u)\| = \|u\| \quad \text{For all } u$$

Example: linear operator T on \mathcal{R}^2 that rotates a vector by θ .

\Rightarrow Is T norm-preserving?

$$A_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Example: linear operator T is reflection

\Rightarrow Is T norm-preserving?

$$A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Norm-preserving

- A linear operator is norm-preserving if

$$\|T(u)\| = \|u\| \quad \text{For all } u$$

Example: linear operator T is projection
 \Rightarrow Is T norm-preserving?

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

Example: linear operator U on \mathcal{R}^n that has an eigenvalue $\lambda \neq \pm 1$.

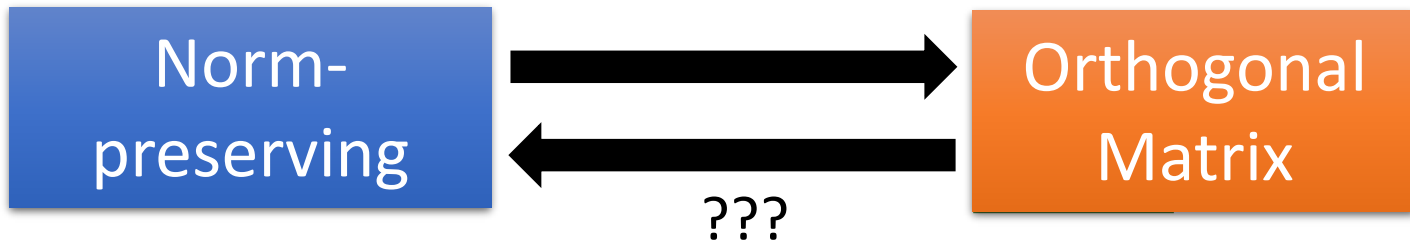
Orthogonal Matrix

- An $n \times n$ matrix Q is called an orthogonal matrix (or simply orthogonal) if the columns of Q form an **orthonormal basis** for \mathbb{R}^n
- Orthogonal operator: standard matrix is an orthogonal matrix.

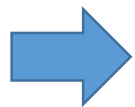
$$A_\theta = \begin{matrix} \begin{matrix} \text{unit} & \text{unit} \end{matrix} \\ \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \\ \text{orthogonal} \end{matrix} \text{ is an orthogonal matrix.}$$

Norm-preserving

- Necessary conditions:

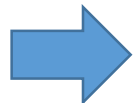


Linear operator Q is norm-preserving



$$\|\mathbf{q}_j\| = 1$$

$$\|\mathbf{q}_j\| = \|Q\mathbf{e}_j\| = \|\mathbf{e}_j\|$$



\mathbf{q}_i and \mathbf{q}_j are orthogonal

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$$\|\mathbf{q}_i + \mathbf{q}_j\|^2 = \|Q\mathbf{e}_i + Q\mathbf{e}_j\|^2 = \|Q(\mathbf{e}_i + \mathbf{e}_j)\|^2 = \|\mathbf{e}_i + \mathbf{e}_j\|^2 = 2 = \|\mathbf{q}_i\|^2 + \|\mathbf{q}_j\|^2$$

Orthogonal Matrix

Those properties are used to check orthogonal matrix.

- Q is an orthogonal matrix
 - $QQ^T = I_n$
 - Q is invertible, and $Q^{-1} = Q^T$
 - $Qu \cdot Qv = u \cdot v$ for any u and v
 - $\|Qu\| = \|u\|$ for any u
- Simple inverse
- Q preserves dot products
- Q preserves norms



Orthogonal Matrix

- Let P and Q be $n \times n$ orthogonal matrices
 - $\det Q = \pm 1$
 - PQ is an orthogonal matrix
 - Q^{-1} is an orthogonal matrix
 - Q^T is an orthogonal matrix

$$\text{Check by } (PQ)^{-1} = (PQ)^T$$

$$\text{Check by } (Q^{-1})^{-1} = (Q^{-1})^T$$

Proof

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{-1}{\sqrt{2}} \\ 0 & 1 & 0 \end{bmatrix}$$

Rows and columns

Orthogonal Operator

- Applying the properties of orthogonal matrices on orthogonal operators
- T is an orthogonal operator
 - $T(u) \cdot T(v) = u \cdot v$ for all u and v
 - $\|T(u)\| = \|u\|$ for all u
- T and U are orthogonal operators, then TU and T^{-1} are orthogonal operators.

Preserves dot product

Preserves norms

Example: Find an orthogonal operator T on \mathcal{R}^3 such that

$$T \left(\begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Norm-preserving

$$v = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix}$$

$$Av = e_2$$

$$v = A^{-1}e_2$$

Find A^{-1} first

Because $A^{-1} = A^T$

$$A^{-1} = \begin{bmatrix} * & 1/\sqrt{2} & * \\ * & 0 & * \\ * & 1/\sqrt{2} & * \end{bmatrix}$$

Also orthogonal

$$A^{-1} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$A = (A^{-1})^T$$

Conclusion

- Orthogonal Matrix (Operator)
 - Columns and rows are orthogonal unit vectors
 - Preserving norms, dot products
 - Its inverse is equal its transpose

Outline

Orthogonal Matrices

- Reference: Chapter 7.5

Symmetric Matrices

- Reference: Chapter 7.6

Eigenvalues are real

- The eigenvalues for symmetric matrices are always **real**.

Consider 2 x 2 symmetric matrices

$$A = A^T = \begin{bmatrix} a & b \\ b & c \end{bmatrix} \in \mathbb{R}^{2 \times 2}$$

How about more general cases?

實係數多項式虛根共軛

$$\det(A - tI_2) = t^2 - (a + c)t + ac - b^2$$

$$\text{Since } (a + c)^2 - 4(ac - b^2) = (a - c)^2 + 4b^2 \geq 0$$

The symmetric matrices always have real eigenvalues.

Orthogonal Eigenvectors

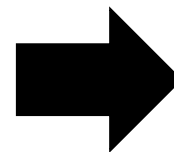
$$\det(A - tI_n) \quad \text{Factorization}$$

A is symmetric

$$= (t - \lambda_1)^{\underline{m_1}} (t - \lambda_2)^{\underline{m_2}} \dots (t - \lambda_k)^{\underline{m_k}} (\dots \dots)$$

Eigenvalue: λ_1 λ_2 λ_k
Eigenspace:
(dimension) $d_1 \leq m_1$ $d_2 \leq m_2$ $d_k \leq m_k$


Independent

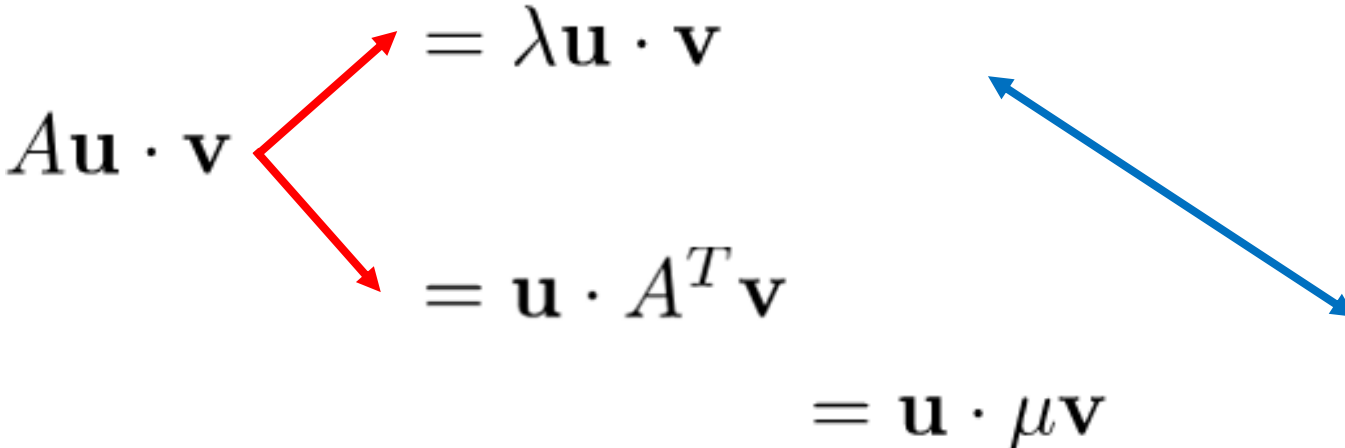


orthogonal

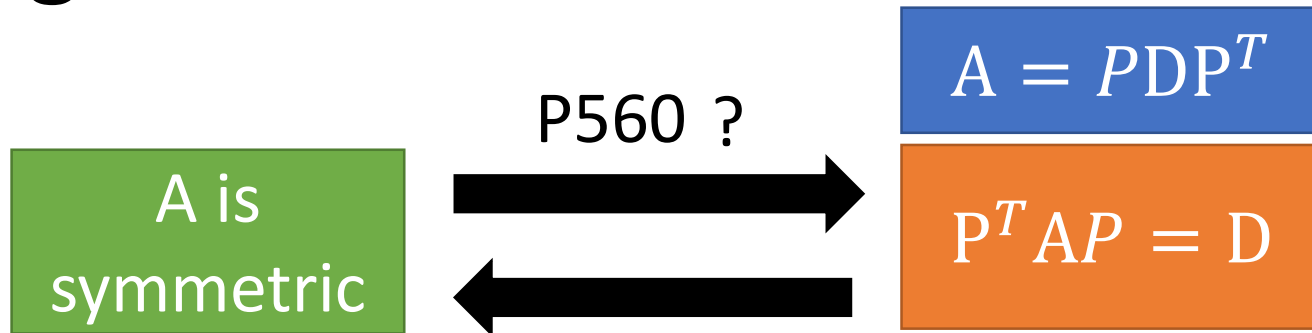
Orthogonal Eigenvectors

- A is symmetric.
- If u and v are eigenvectors corresponding to eigenvalues λ and μ ($\lambda \neq \mu$)

 u and v are orthogonal.

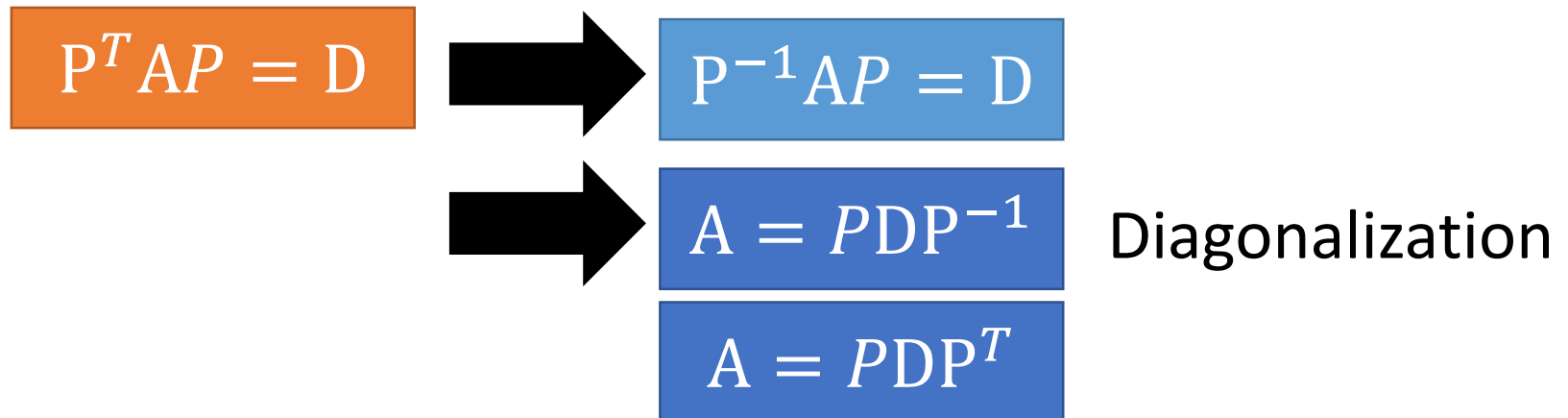
$$\begin{aligned} \mathbf{A}\mathbf{u} \cdot \mathbf{v} &= \lambda \mathbf{u} \cdot \mathbf{v} \\ &= \mathbf{u} \cdot \mathbf{A}^T \mathbf{v} \\ &= \mathbf{u} \cdot \mu \mathbf{v} \end{aligned}$$


Diagonalization



P is an orthogonal matrix
D is a diagonal matrix

← : simple



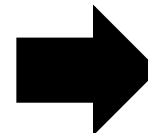
P consists of eigenvectors , D are eigenvalues

Diagonalization

- Example

$$A = \begin{bmatrix} 2 & -2 \\ -2 & 5 \end{bmatrix}$$

$$A = PDP^{-1}$$



$$A = PDP^T$$

$$P^T AP = D$$

A has eigenvalues $\lambda_1 = 6$ and $\lambda_2 = 1$,

with corresponding eigenspaces $\mathcal{E}_1 = \text{Span}\{[-1 \ 2]^T\}$ and $\mathcal{E}_2 = \text{Span}\{[2 \ 1]^T\}$

$\Rightarrow \mathcal{B}_1 = \{[-1 \ 2]^T/\sqrt{5}\}$ and $\mathcal{B}_2 = \{[2 \ 1]^T/\sqrt{5}\}$

orthogonal

$$P = \frac{1}{\sqrt{5}} \begin{bmatrix} -1 & 2 \\ 2 & 1 \end{bmatrix} \text{ and } D = \begin{bmatrix} 6 & 0 \\ 0 & 1 \end{bmatrix}.$$

Example of Diagonalization of Symmetric Matrix

$$A = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$

$$A = PDP^{-1}$$

$$A = PDP^T$$

P is an orthogonal matrix

$$\lambda_1 = 2$$

Intendent

Gram-

Schmidt

$$\text{Eigenspace: } \text{Span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$



$$\text{Span} \left\{ \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}, \begin{bmatrix} 1/\sqrt{6} \\ 1/\sqrt{6} \\ -2/\sqrt{6} \end{bmatrix} \right\}$$

normalization

$$\lambda_2 = 8$$

Not orthogonal

$$\text{Eigenspace: } \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$



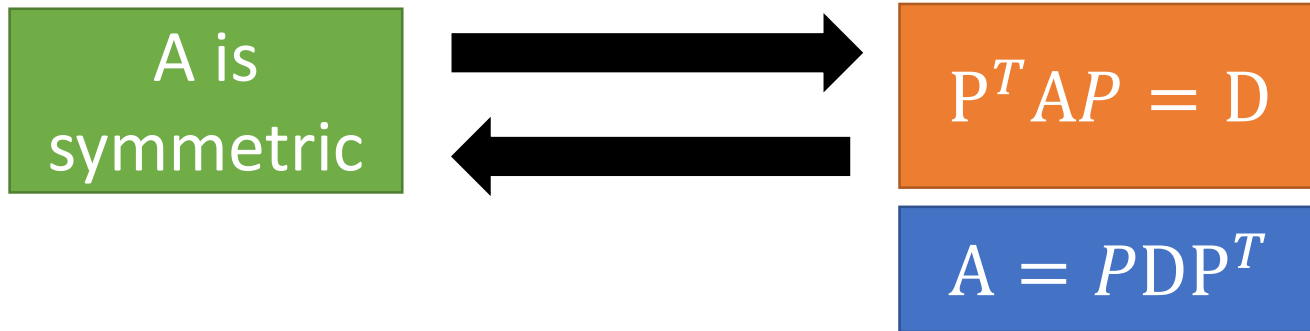
$$\text{Span} \left\{ \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix} \right\}$$

$$P = \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & 1/\sqrt{6} & 1/\sqrt{3} \\ 0 & -2/\sqrt{6} & 1/\sqrt{3} \end{bmatrix}$$

$$D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix}$$

Diagonalization

P is an orthogonal matrix



P consists of eigenvectors , D are eigenvalues

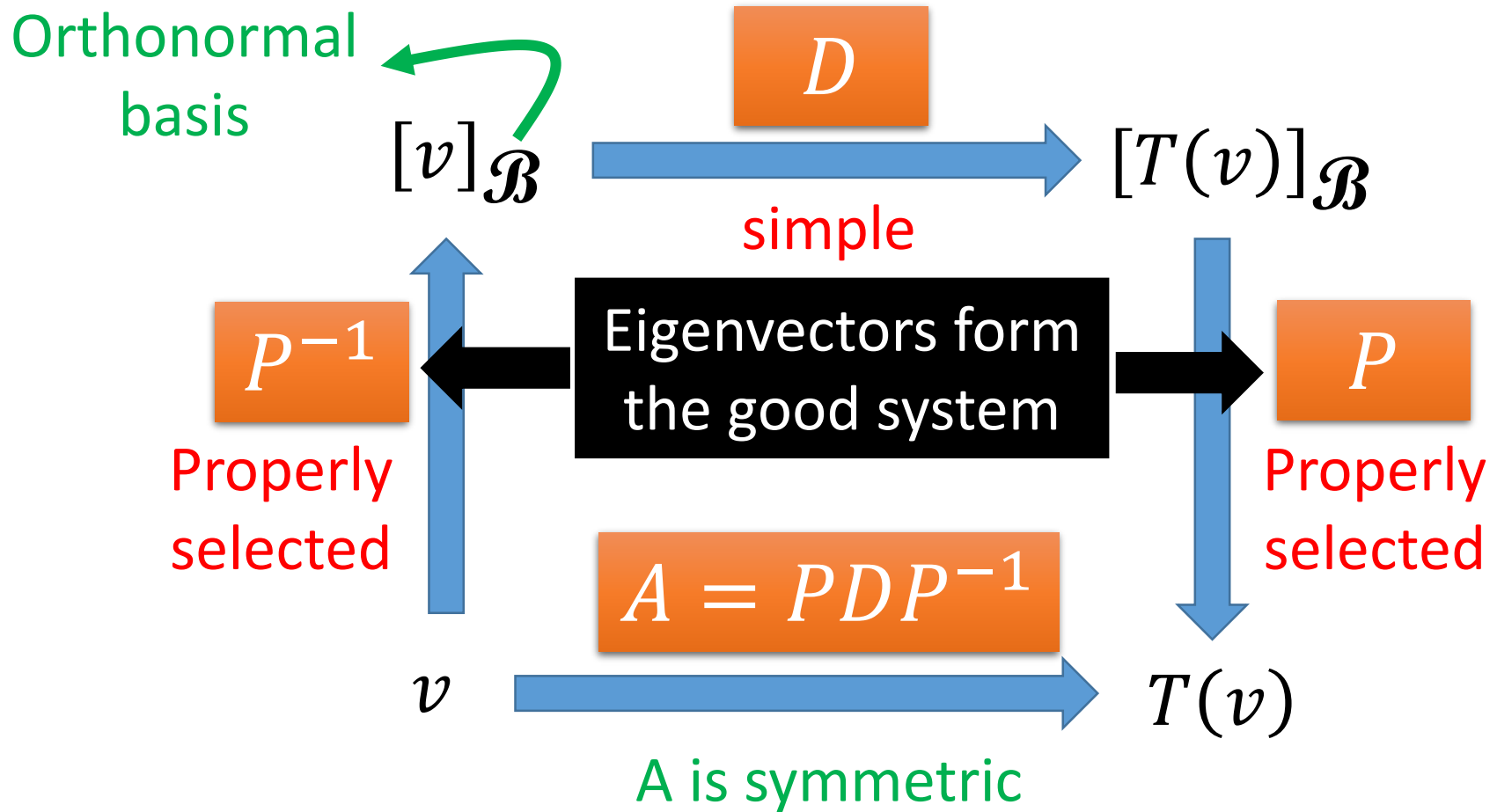
Finding an orthonormal basis consisting of eigenvectors of A

Diagonalization of Symmetric Matrix

$$u = \underbrace{c_1}_{\downarrow} v_1 + \underbrace{c_2}_{\downarrow} v_2 + \cdots + \underbrace{c_k}_{\downarrow} v_k$$

$$u \cdot v_1 \quad u \cdot v_2 \quad u \cdot v_k$$

Orthonormal basis



Spectral Decomposition

Orthonormal basis

$$A = PDP^T \quad \text{Let } P = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_n] \text{ and } D = \text{diag}[\lambda_1 \ \lambda_2 \ \cdots \ \lambda_n].$$

$$= P[\lambda_1 \mathbf{e}_1 \ \lambda_2 \mathbf{e}_2 \ \cdots \ \lambda_n \mathbf{e}_n]P^T$$

$$= [\lambda_1 P\mathbf{e}_1 \ \lambda_2 P\mathbf{e}_2 \ \cdots \ \lambda_n P\mathbf{e}_n]P^T$$

$$= [\lambda_1 \mathbf{u}_1 \ \lambda_2 \mathbf{u}_2 \ \cdots \ \lambda_n \mathbf{u}_n] \begin{bmatrix} \mathbf{u}_1^T \\ \mathbf{u}_2^T \\ \vdots \\ \mathbf{u}_n^T \end{bmatrix}$$

P_1

P_2

P_n

$$= \lambda_1 P_1 + \lambda_2 P_2 + \cdots + \lambda_n P_n \quad P_i \text{ are symmetric}$$

Spectral Decomposition

Orthonormal basis

$A = PDP^T$ Let $P = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_n]$ and $D = \text{diag}[\lambda_1 \ \lambda_2 \ \cdots \ \lambda_n]$.

$$= \lambda_1 P_1 + \lambda_2 P_2 + \cdots + \lambda_n P_n$$

$$\text{rank } P_i = \text{rank } \mathbf{u}_i \mathbf{u}_i^T = 1.$$

$$P_i P_i = \mathbf{u}_i \mathbf{u}_i^T \mathbf{u}_i \mathbf{u}_i^T = \mathbf{u}_i \mathbf{u}_i^T$$

$$P_i P_j = \mathbf{u}_i \mathbf{u}_i^T \mathbf{u}_j \mathbf{u}_j^T = O$$

$$P_i \mathbf{u}_i$$

$$P_i \mathbf{u}_j$$

Spectral Decomposition

- Example

$$A = \begin{bmatrix} 3 & -4 \\ -4 & -3 \end{bmatrix} \quad \text{Find spectrum decomposition.}$$

Eigenvalues $\lambda_1 = 5$ and $\lambda_2 = -5$.

$$P_1 = u_1 u_1^T$$

An orthonormal basis consisting of eigenvectors of A is

$$B = \left\{ \begin{bmatrix} -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix} \right\}$$

$u_1 \qquad u_2$

$$P_2 = u_2 u_2^T$$

$$A = \lambda_1 P_1 + \lambda_2 P_2$$

Conclusion

- Any symmetric matrix
 - has only real eigenvalues
 - has orthogonal eigenvectors.
 - is always diagonalizable



P is an orthogonal matrix

Appendix

Diagonalization

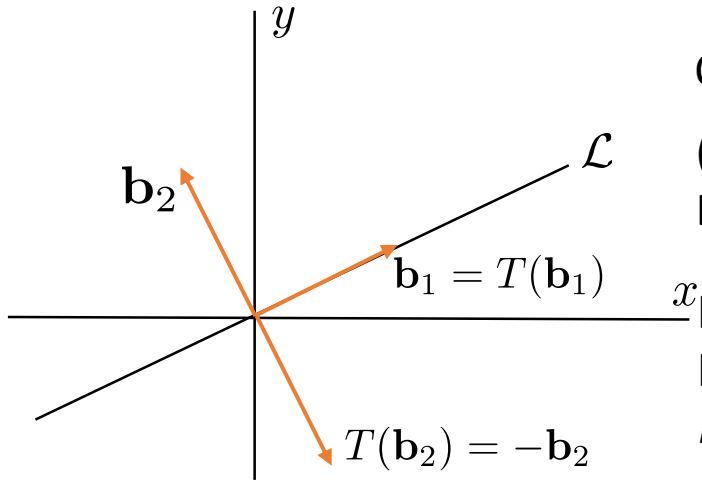
- By induction on n .
- $n = 1$ is obvious.
- Assume it holds for $n \geq 1$, and consider $A \in \mathcal{R}^{(n+1) \times (n+1)}$.
- A has an eigenvector $\mathbf{b}_1 \in \mathcal{R}^{n+1}$ corresponding to a real eigenvalue λ , so \exists an orthonormal basis $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_{n+1}\}$
 - by the **Extension Theorem** and Gram-Schmidt Process.

$$\begin{aligned}
B^T AB &= \begin{bmatrix} \mathbf{b}_1^T \\ \mathbf{b}_2^T \\ \vdots \\ \mathbf{b}_{n+1}^T \end{bmatrix} \begin{bmatrix} A\mathbf{b}_1 & A\mathbf{b}_2 & \cdots & A\mathbf{b}_{n+1} \end{bmatrix} = \begin{bmatrix} \mathbf{b}_1^T A\mathbf{b}_1 & \mathbf{b}_1^T A\mathbf{b}_2 & \cdots & \mathbf{b}_1^T A\mathbf{b}_{n+1} \\ \mathbf{b}_2^T A\mathbf{b}_1 & \mathbf{b}_2^T A\mathbf{b}_2 & \cdots & \mathbf{b}_2^T A\mathbf{b}_{n+1} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{b}_{n+1}^T A\mathbf{b}_1 & \mathbf{b}_{n+1}^T A\mathbf{b}_2 & \cdots & \mathbf{b}_{n+1}^T A\mathbf{b}_{n+1} \end{bmatrix} \\
&= \left[\begin{array}{c|c} \lambda & \mathbf{0}^T \\ \hline \mathbf{0} & S \end{array} \right], \text{ since } \mathbf{b}_1^T A\mathbf{b}_1 = \lambda \mathbf{b}_1^T \mathbf{b}_1 = \lambda \text{ and } \mathbf{b}_j^T A\mathbf{b}_1 = \mathbf{b}_1^T A\mathbf{b}_j = 0 \forall j \neq 1.
\end{aligned}$$

$S = S^T \in \mathcal{R}^{n \times n} \Rightarrow \exists$ an orthogonal $C \in \mathcal{R}^{n \times n}$ and a diagonal $L \in \mathcal{R}^{n \times n}$ such that $C^T S C = L$ by the induction hypothesis.

$$\Rightarrow \underbrace{\begin{bmatrix} \mathbf{1} & \mathbf{0}^T \\ \mathbf{0} & C^T \end{bmatrix}}_{\text{orthogonal } P^T} B^T AB \underbrace{\begin{bmatrix} \mathbf{1} & \mathbf{0}^T \\ \mathbf{0} & C \end{bmatrix}}_{\text{orthogonal } P} = \begin{bmatrix} \mathbf{1} & \mathbf{0}^T \\ \mathbf{0} & C^T \end{bmatrix} \begin{bmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & S \end{bmatrix} \begin{bmatrix} \mathbf{1} & \mathbf{0}^T \\ \mathbf{0} & C \end{bmatrix} = \begin{bmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & C^T S C \end{bmatrix} = \underbrace{\begin{bmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & L \end{bmatrix}}_{\text{diagonal } D}$$

Example: reflection operator T about a line \mathcal{L} passing the origin.



Question: Is T an orthogonal operator?

(An easier) Question:

Is T orthogonal if \mathcal{L} is the x -axis?

\mathbf{b}_1 is a **unit vector along \mathcal{L}** .

\mathbf{b}_2 is a **unit vector perpendicular to \mathcal{L}** .

$P = [\mathbf{b}_1 \ \mathbf{b}_2]$ is **an orthogonal matrix**.

$\mathcal{B} = \{ \mathbf{b}_1, \mathbf{b}_2 \}$ is an orthonormal basis of \mathcal{R}^2 .

$[T]_{\mathcal{B}} = \text{diag}[1 \ -1]$ is **an orthogonal matrix**.

Let the standard matrix of T be Q . Then $[T]_{\mathcal{B}} = P^{-1}QP$, or $Q = P[T]_{\mathcal{B}}P^{-1} \Rightarrow Q$ is an orthogonal matrix. $\Rightarrow T$ is an orthogonal operator.